

Equations

| | |
|--|-------------------------------------|
| current = $\frac{\text{voltage}}{\text{resistance}}$ | $I = \frac{V}{R}$ |
| total resistance in a series circuit | $R = R_1 + R_2$ |
| energy transferred = power \times time | $E = Pt$ |
| power = voltage \times current | $P = VI$ |
| % efficiency = $\frac{\text{energy [or power] usefully transferred}}{\text{total energy [or power] supplied}} \times 100$ | |
| density = $\frac{\text{mass}}{\text{volume}}$ | $\rho = \frac{m}{V}$ |
| units used (kWh) = power (kW) \times time (h) cost = units used \times cost per unit | |
| wave speed = wavelength \times frequency | $v = \lambda f$ |
| speed = $\frac{\text{distance}}{\text{time}}$ | |
| pressure = $\frac{\text{force}}{\text{area}}$ | $p = \frac{F}{A}$ |
| change in thermal energy = mass \times specific heat capacity \times change in temperature | $\Delta Q = mc\Delta\theta$ |
| thermal energy for a change of state = mass \times specific latent heat | $Q = mL$ |
| V_1 = voltage across the primary coil V_2 = voltage across the secondary coil N_1 = number of turns on the primary coil N_2 = number of turns on the secondary coil | $\frac{V_1}{V_2} = \frac{N_1}{N_2}$ |

SI multipliers

| Prefix | Multiplier |
|--------|--------------------|
| m | 1×10^{-3} |
| k | 1×10^3 |
| M | 1×10^6 |

Equations

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| current = $\frac{\text{voltage}}{\text{resistance}}$ | $I = \frac{V}{R}$ |
| total resistance in a series circuit | $R = R_1 + R_2$ |
| total resistance in a parallel circuit | $\frac{1}{R} = \frac{1}{R_1} + \frac{1}{R_2}$ |
| energy transferred = power \times time | $E = Pt$ |
| power = voltage \times current | $P = VI$ |
| power = current ² \times resistance | $P = I^2 R$ |
| % efficiency = $\frac{\text{energy [or power] usefully transferred}}{\text{total energy [or power] supplied}} \times 100$ | |
| density = $\frac{\text{mass}}{\text{volume}}$ | $\rho = \frac{m}{V}$ |
| units used (kWh) = power (kW) \times time (h) cost = units used \times cost per unit | |
| wave speed = wavelength \times frequency | $v = \lambda f$ |
| speed = $\frac{\text{distance}}{\text{time}}$ | |
| pressure = $\frac{\text{force}}{\text{area}}$ | $p = \frac{F}{A}$ |
| p = pressure V = volume T = kelvin temperature | $\frac{pV}{T} = \text{constant}$ |
| | $T / \text{K} = \theta / ^\circ\text{C} + 273$ |
| change in thermal energy = mass \times specific heat capacity \times change in temperature | $\Delta Q = mc\Delta\theta$ |
| thermal energy for a change of state = mass \times specific latent heat | $Q = mL$ |
| force on a conductor (at right angles to a magnetic field) carrying a current = magnetic field strength \times current \times length | $F = BIl$ |
| V_1 = voltage across the primary coil V_2 = voltage across the secondary coil N_1 = number of turns on the primary coil N_2 = number of turns on the secondary coil | $\frac{V_1}{V_2} = \frac{N_1}{N_2}$ |

SI multipliers

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|--------|---------------------|
| p | 1×10^{-12} |
| n | 1×10^{-9} |
| μ | 1×10^{-6} |
| m | 1×10^{-3} |

| Prefix | Multiplier |
|--------|--------------------|
| k | 1×10^3 |
| M | 1×10^6 |
| G | 1×10^9 |
| T | 1×10^{12} |

Equations

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| speed = $\frac{\text{distance}}{\text{time}}$ | |
| acceleration [or deceleration] = $\frac{\text{change in velocity}}{\text{time}}$ | $a = \frac{\Delta v}{t}$ |
| acceleration = gradient of a velocity-time graph | |
| resultant force = mass \times acceleration | $F = ma$ |
| weight = mass \times gravitational field strength | $W = mg$ |
| work = force \times distance | $W = Fd$ |
| force = spring constant \times extension | $F = kx$ |
| momentum = mass \times velocity | $p = mv$ |
| force = $\frac{\text{change in momentum}}{\text{time}}$ | $F = \frac{\Delta p}{t}$ |
| u = initial velocity v = final velocity t = time a = acceleration x = displacement | $v = u + at$ $x = \frac{u + v}{2}t$ |
| moment = force \times distance | $M = Fd$ |

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| speed = $\frac{\text{distance}}{\text{time}}$ | |
| acceleration [or deceleration] = $\frac{\text{change in velocity}}{\text{time}}$ | $a = \frac{\Delta v}{t}$ |
| acceleration = gradient of a velocity-time graph | |
| distance travelled = area under a velocity-time graph | |
| resultant force = mass \times acceleration | $F = ma$ |
| weight = mass \times gravitational field strength | $W = mg$ |
| work = force \times distance | $W = Fd$ |
| kinetic energy = $\frac{\text{mass} \times \text{velocity}^2}{2}$ | $\text{KE} = \frac{1}{2}mv^2$ |
| change in potential energy = mass \times gravitational field strength \times change in height | $\text{PE} = mgh$ |
| force = spring constant \times extension | $F = kx$ |
| work done in stretching = area under a force-extension graph | $W = \frac{1}{2}Fx$ |
| momentum = mass \times velocity | $p = mv$ |
| force = $\frac{\text{change in momentum}}{\text{time}}$ | $F = \frac{\Delta p}{t}$ |
| u = initial velocity v = final velocity t = time a = acceleration x = displacement | $v = u + at$ $x = \frac{u + v}{2}t$ $x = ut + \frac{1}{2}at^2$ $v^2 = u^2 + 2ax$ |
| moment = force \times distance | $M = Fd$ |

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